

# Selected Readings in Micro: Multi-Echelon System

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## Multi-Echelon Production/Inventory Theory

- ▶ these lecture notes are based on G.J. van Houtum's review paper: "Multi-Echelon Production/Inventory Systems: Optimal Policies, Heuristics, and Algorithms," appeared in *Tutorials in Operations Research*, 2006 INFORMS

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- ▶ multi-echelon theory: originated from Clark and Scarf ("Optimal policies for a multi-echelon inventory problem," *Management Science*, 1960)
- ▶ Clark-Scarf model: a supply chain consisting of multiple stages with a serial structure
  - ▶ stage  $N$  orders at an external supplier, stage  $N - 1$  orders at stage  $N$ , ..., stage 1 faces external demand
  - ▶ stage may represent a production node, or a transportation node
  - ▶ time consists of periods of equal length, e.g., days, weeks or months, and the time horizon is infinite

## Two-Echelon Serial System

- ▶ a supply chain with two stages: upstream stage is called stage 2 and the downstream stage is called stage 1

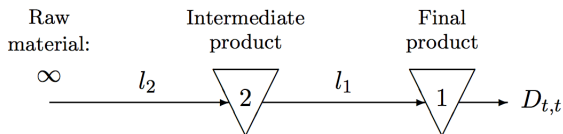
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Figure 1: The serial, two-echelon production/inventory system.



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  - ▶ an amount ordered by stage 2 (1) arrives at stockpoint 2 (1) after a deterministic leadtime  $l_2$  ( $l_1$ )
- ▶ inventory constraints
  - ▶ there is always sufficient raw material available and thus orders by stockpoint 2 are never delayed
  - ▶ if the available stock at stockpoint 2 is smaller than the ordered amount by stage 1, then the available amount is sent to stage 1 while the rest is delivered as soon as possible

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- ▶ for simplicity, we assume the demands in different periods are i.i.d., following some distribution  $F$  with mean  $\mu > 0$

# Timing of Events

- ▶ in each period, the following events happen in order
  1. at each stage, an order is placed
  2. arrival of orders
  3. demand occurs
  4. one-period costs are assessed

## Echelon Inventory Level/Position

- ▶ *echelon inventory level* (or *echelon stock*) of a given stockpoint: all physical stock at that stockpoint plus all materials in transit to or on hand at any stockpoint downstream minus eventual backlogs at the most downstream stock points
  - ▶ the chain under consideration is called the *echelon*

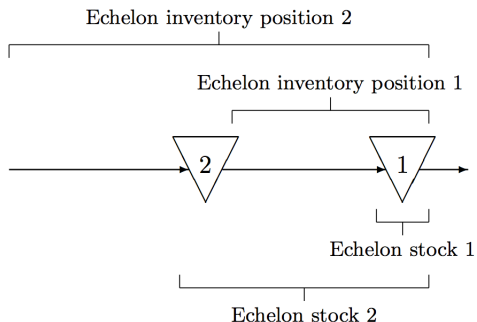
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- ▶ echelon inventory position of a stockpoint: its echelon inventory level plus all materials which are in transit to the stockpoint



# Echelon Inventory Level/Position

Figure 2: The concepts echelon stock and echelon inventory position.



## Echelon Cost

- ▶ for  $n = 1, 2$ , we pay costs  $c_n(x_n)$ , where  $x_n$  denotes echelon stock  $n$  at the end of a period
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- ▶ assumption: the cost functions  $c_n(x_n)$ ,  $n = 1, 2$ , are convex and coercive (it is suboptimal to let the backlog grow to infinity)
- ▶ special case: linear holding and penalty costs

$$\underbrace{h_2}_{\text{holding cost at 1}} (x_2 - x_1)_+ + \underbrace{(h_1 + h_2)}_{\text{holding cost at 2}} (x_1)_+ + \underbrace{p}_{\text{penalty cost}} (x_1)_- = c_2(x_2) + c_1(x_1) \quad (1)$$

where  $c_2(x_2) = h_2 x_2$  and  $c_1(x_1) = h_1 x_1 + (p + h_1 + h_2)(x_1)_-$

# Objective Function

- ▶ minimize the average costs per period

$$\min_{\pi \in \Pi} G(\pi) = \lim_{T \rightarrow \infty} \frac{1}{T} E \left[ \sum_{t=0}^{T-1} (C_{t,2} + C_{t,1}) \right]$$

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- ▶ simplification assumptions: no discounting, no ordering cost
  - ▶ make the key intuition transparent
  - ▶ many insights extend to more complicated settings

## Decision Cycle at Time $t_0$

- ▶ stage 2's decision at the beginning of period  $t_0$ : order such that the echelon inventory position  $IP_{t_0,2}$  becomes some level  $z_2$ , which affects the expected cost at the end of period  $t_0 + l_2$ , i.e.,

$$E [C_{t_0+l_2,2} | IP_{t_0,2} = z_2] = E [c_2 (z_2 - D_{t_0,t_0+l_2})]$$

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- ▶ stage 1's decision at the beginning of period  $t_0 + l_2$ : order such that  $IP_{t_0+l_2,1}$  becomes some level  $z_1$ , which affects the expected cost of echelon 1 at the end of period  $t_0 + l_2 + l_1$ , i.e.,

$$E [C_{t_0+l_2+l_1,1} | IP_{t_0+l_2,1} = z_1] = E [c_1 (z_1 - D_{t_0+l_2,t_0+l_2+l_1})]$$



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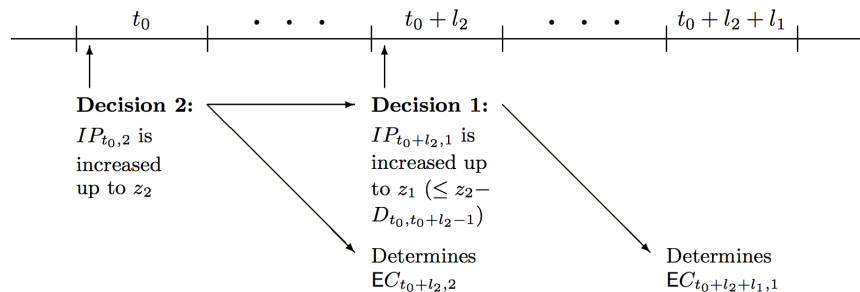
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- ▶ these two decisions are interdependent: stage 2's decision at  $t_0 + l_2$  leads to the echelon inventory level  $IL_{t_0+l_2,2} = z_2 - D_{t_0,t_0+l_2-1}$ , which directly limits the level to which stage 1 can increase  $IP_{t_0+l_2,1}$ , i.e.,

$$z_1 \leq z_2 - D_{t_0,t_0+l_2-1}$$

# Illustration

Figure 3: The consequences of the decisions 1 and 2.



## The Relaxed Single-Cycle Problem

- ▶ we consider how the decisions 1 and 2 can be taken such that the expected total costs attached to cycle  $t_0$  are minimized, i.e.,

$$\min_{(z_1, z_2): z_1 \leq z_2 - D_{t_0, t_0+l_2-1}} E [c_2 (z_2 - D_{t_0, t_0+l_2})] + E [c_1 (z_1 - D_{t_0+l_2, t_0+l_2+l_1})]$$

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- ▶ the idea is to solve this “static” problem first, and it turns out that the solution to this “myopic” problem is also the optimal solution for the full infinite-horizon problem under mild assumptions
- ▶ this problem has the same structure as a 2-period dynamic programming problem: Clark-Scarf’s key insight is to solve the multi-echelon problem by mimicking the idea of dynamic programming, i.e., treating the series of decisions on the supply chain as the series of decision over time

## The Optimal Choice for $z_1$

- ▶ define a function

$$G_1(y_1) \equiv E [c_1 (z_1 - D_{t_0+l_2, t_0+l_2+l_1})]$$

- ▶ the expected costs attached to echelon 1 at the end of a period  $t_0 + l_2 + l_1$  if echelon inventory position 1 at the beginning of period  $t_0 + l_2$  has been increased up to level  $y_1$
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  - ▶ interpretation: cost associated with the subsystem that consists of stage 1 only and has stockpoint 2 as external supplier with infinite supply
- ▶ result:  $G_1(y_1)$  is convex in  $y_1$  and  $S_1 \equiv \arg \min_{y_1} G_1(y_1)$  defines a order-up-to/base-stock policy

$$\begin{aligned} z_1 &= \min \{IL_{t_0+l_2, 2}, S_1\} \\ &= \min \{y_2 - D_{t_0, t_0+l_2-1}, S_1\} \end{aligned}$$

- ▶ optimal policy depends on  $y_2$  because of the natural constraint induced by the inventory level at stockpoint 2

## Optimal Choice for $z_2$

- ▶ define a function

$$G_2(y_1, y_2) = E [c_2 (y_2 - D_{t_0, t_0+l_2}) \\ + c_1 (\min \{y_2 - D_{t_0, t_0+l_2-1}, y_1\} - D_{t_0+l_2, t_0+l_2+l_1})]$$

- ▶ expected cycle cost when  $y_1$  and  $y_2$  are the basestock/order-up-to levels for decisions at stockpoints 1 and 2



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- ▶ result:  $G_2(S_1, y_2)$  is convex in  $y_2$  and  $S_2 \equiv \arg \min_{y_2} G_2(S_1, y_2)$  defines a order-up-to/base-stock policy that is optimal
  - ▶ the dependence of  $S_2$  on  $S_1$  comes from the additional penalty costs when echelon stock 2 is insufficient to increase echelon inventory position 1 to its optimal value  $S_1$  (“induced penalty cost” called by Clark and Scarf)

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- ▶ decomposition result: optimal base-stock levels can be obtained sequentially by the minimization of one-dimensional functions

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- ▶ assume the echelon cost functions are linear and given by (1)

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where  $B_0^{(1)} = (D_{t_0+l_2, t_0+l_2+l_1} - S_1)_+$  represents the backlog at stockpoint 1 for echelon 1

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- ▶ for a given optimal basestock level  $S_1$  for echelon 1, the optimal basestock level  $S_2$  for echelon 2 is such that

$$\Pr \left\{ B_0^{(2)} = 0 \right\} = \frac{p}{p + h_1 + h_2}$$

where  $B_0^{(2)} = \left( B_1^{(2)} + D_{t_0+l_2, t_0+l_2+l_1} - S_1 \right)_+$  (with

$B_1^{(2)} = (D_{t_0, t_0+l_2-1} - (S_2 - S_1))_+$ ) represent the backlog at stockpoint 1 for echelon 2

- ▶ non-stockout probability is lower when both stockpoints are considered

# Extensions

- ▶ continuous review: continuous-time version of the periodic review version we have discussed
- ▶ discrete product: order amounts and inventory levels are discrete variables
- ▶ discounted costs: minimizing discounted expected costs
- ▶ target service level: minimizing costs subject to service level constraint
- ▶ assembly systems, distribution and general systems
- ▶ many more ...

## Next Class Paper

- ▶ Jovanovic, B: "Selection and the evolution of industry,"  
*Econometrica*, 1982